

Module: Advanced Machine Vision

Level	Master	Short Name	AMV
Responsible Lecturers	Prof. Dr. Ralph Hänsel		
Department, Facility	Electrical Engineering and Computer Science		
Course of Studies	Applied Information Technology, Master		
Compulsory/elective	Compulsory elective	ECTS Credit Points	5
Semester of Studies	(Unspecified)	Semester Hours per Week	4
Length (semesters)	1	Workload (hours)	150
Frequency	WiSe	Presence Hours	60
Teaching Language	German/English	Self-Study Hours	90

The following section is filled only if there is **exactly one** module-concluding exam.

Exam Type	Portfolio Exam	Exam Language	German/English	
Exam Length (minutes)		Exam Grading System	One-third Grades	
Learning Outcomes	 Students can describe the main functionalities of the robot operating system 2 (ROS2) Students can integrate new functional blocks into ROS2 Students can describe basic deep learning architectures for object detection and other tasks in machine vision Students can perform the training of a given object detector model on a custom dataset and evaluate the performance Students can apply different depth estimation technologies to estimate the position of a detected object Students can describe technologies for ego-motion estimation and joint map generation (SLAM) Students can state the physical description of light 			
Participation Prerequisites				
The previous section is filled only if there is exactly one module-concluding exam.				
Consideration of Gender and Diversity Issues	 Use of gender-ne Target group spe Making subject d 	eutral language (THL standard) cific adjustment of didactic meth iversity visible (female researche	ods ers, cultures etc.)	
Applicability	Robotics			
Remarks				



Module Course: Advanced Machine Vision (Lecture)

(of Module: Advanced Machine Vision)

Course Type	Lecture	Form of Learning	Presence		
Mandatory Attendance	no	ECTS Credit Points	3		
Participation Limit		Semester Hours per Week	3		
Group Size		Workload (hours)	90		
Teaching Language	German/English	Presence Hours	45		
Study Achievements ("Studienleistung", SL)		Self-Study Hours	45		
SL Length (minutes)		SL Grading System			
The following section is filled only if there is a course-specific exam.					
Exam Type		Exam Language			
Exam Length (minutes)		Exam Grading System			
Learning Outcomes					
Participation Prerequisites					
The previous section is filled only if there is a course-specific exam.					
Contents	The course is focused on autonomous driving and how vision can play an important role as a sensor in an autonomous robot Processing Environment (ROS2) Image and Light Deep Learning in Machine Vision Environment Model Functional Safety Aspects				
Literature	Literature will be given in the lecture				
Remarks					



Module Course: Advanced Machine Vision (Lab)

(of Module: Advanced Machine Vision)

Course Type	Practical Training	Form of Learning	Presence		
Mandatory Attendance	no	ECTS Credit Points	2		
Participation Limit		Semester Hours per Week	1		
Group Size	12	Workload (hours)	60		
Teaching Language	German/English	Presence Hours	15		
Study Achievements ("Studienleistung", SL)		Self-Study Hours	45		
SL Length (minutes)		SL Grading System			
The following section is filled only if there is a course-specific exam.					
Exam Type		Exam Language			
Exam Length (minutes)		Exam Grading System			
Learning Outcomes					
Participation Prerequisites					
The previous section is filled only if there is a course-specific exam.					
Contents	See lecture				
Literature	See lecture				
Remarks					