

## Module: Digital Control Systems

<b>Level</b>	Bachelor	<b>Short Name</b>	CS II
<b>Responsible Lecturers</b>	Bayerlein, Jörg, Prof. Dr.		
<b>Department, Facility</b>	Electrical Engineering and Computer Science		
<b>Course of Studies</b>	Electrical Engineering - Communication Systems, Bachelor		
<b>Compulsory/elective</b>	Compulsory	<b>ECTS Credit Points</b>	5
<b>Semester of Studies</b>	6	<b>Semester Hours per Week</b>	4
<b>Length (semesters)</b>	1	<b>Workload (hours)</b>	150
<b>Frequency</b>	SuSe	<b>Presence Hours</b>	57
<b>Teaching Language</b>	English	<b>Self-Study Hours</b>	93

The following section is filled only if there is **exactly one** module-concluding exam.

<b>Exam Type</b>	Written Exam	<b>Exam Language</b>	English
<b>Exam Length (minutes)</b>	90	<b>Exam Grading System</b>	Pass
<b>Learning Outcomes</b>	The students should learn to convert a classical PIDT1 into a digital algorithm with rectangular approach. They should be able to work with Z-Transform to Design controllers and filters. They should be able to apply PC-based identification algorithms like step response with Least square optimization, Least square offline and online methods. They should be able to apply some special controllers like model based controllers		
<b>Participation Prerequisites</b>	Control System Basics		

The previous section is filled only if there is **exactly one** module-concluding exam.

<b>Consideration of Gender and Diversity Issues</b>	<ul style="list-style-type: none"> <li>✘ Use of gender-neutral language (THL standard)</li> <li>✘ Target group specific adjustment of didactic methods</li> <li>✘ Making subject diversity visible (female researchers, cultures etc.)</li> </ul>
<b>Applicability</b>	
<b>Remarks</b>	

## Module Course: Digital Control Systems (lecture)

(of Module: Digital Control Systems)

<b>Course Type</b>	Lecture	<b>Form of Learning</b>	Presence
<b>Mandatory Attendance</b>	yes	<b>ECTS Credit Points</b>	4
<b>Participation Limit</b>		<b>Semester Hours per Week</b>	3
<b>Group Size</b>		<b>Workload (hours)</b>	120
<b>Teaching Language</b>	English	<b>Presence Hours</b>	45
<b>Study Achievements ("Studienleistung", SL)</b>		<b>Self-Study Hours</b>	75
<b>SL Length (minutes)</b>		<b>SL Grading System</b>	

The following section is filled only if there is a course-specific exam.

<b>Exam Type</b>		<b>Exam Language</b>	
<b>Exam Length (minutes)</b>		<b>Exam Grading System</b>	
<b>Learning Outcomes</b>	See above.		
<b>Participation Prerequisites</b>	CS I		

The previous section is filled only if there is a course-specific exam.

<b>Contents</b>	Basics of digital PID control, basics of z-transform, some identification methods, some sophisticated controllers like model based controllers
<b>Literature</b>	
<b>Remarks</b>	

## Module Course: Digital Control Systems (Practical Training)

(of Module: Digital Control Systems)

<b>Course Type</b>	Practical Training	<b>Form of Learning</b>	Presence
<b>Mandatory Attendance</b>	yes	<b>ECTS Credit Points</b>	1
<b>Participation Limit</b>		<b>Semester Hours per Week</b>	1
<b>Group Size</b>		<b>Workload (hours)</b>	30
<b>Teaching Language</b>		<b>Presence Hours</b>	12
<b>Study Achievements ("Studienleistung", SL)</b>	Practical Training	<b>Self-Study Hours</b>	18
<b>SL Length (minutes)</b>		<b>SL Grading System</b>	Participation

The following section is filled only if there is a course-specific exam.

<b>Exam Type</b>		<b>Exam Language</b>	
<b>Exam Length (minutes)</b>		<b>Exam Grading System</b>	
<b>Learning Outcomes</b>	The students should be able to design, implement on PC and test some sophisticated loops (position control, inverted pendulum, adaptive controllers)		
<b>Participation Prerequisites</b>	CS I		

The previous section is filled only if there is a course-specific exam.

<b>Contents</b>	Position control system, inverted pendulum, Adaptive controller
<b>Literature</b>	
<b>Remarks</b>	