

Studiengang: Bachelor of Science Maschinenbau <i>Program:</i> Bachelor of Science in Mechanical Engineering					
1	Modul: Modelling and Numerical Analysis <i>Module:</i>				Englisch <i>German</i>
		Semester <i>Semester</i>	Dauer <i>Duration</i>	Status <i>Status</i>	Turnus <i>Regular cycle</i>
		5. Semester	1 Semester	Pflichtfach	jährlich
	Kreditpunkte <i>Credits</i>	Aufwand <i>Workload</i>	Kontaktzeit <i>Contact-hours</i>	Selbststudium <i>Student's efforts</i>	Gruppengröße <i>Team size</i>
	5 ECTS	150h	4 SWS = 60h Vorlesung	30h Vor-/Nachbereitung 60h Übungen	10 – 20 Pers. Lehre
2	Beschreibung <i>Description</i> The simulation of dynamical systems on a computer is of increasing importance for the conception, construction, performance analysis and maintenance of technical systems. It is possible to answer very detailed questions even in the case where the system consists only as a model on a computer. In the lecture, it will be shown how to derive a mathematical model from the physical laws. It will also be explained how this mathematical model can be implemented on a computer and how it can be applied.				
3	Lernziele <i>Learning Outcomes</i> The students are asked to learn <ul style="list-style-type: none"> • how to derive the differential equations which describe the dynamics of the system by using the underlying physical laws • how the mathematical model can be implemented on a computer and how hardware can be embedded • about the most important properties of nonlinear and linear dynamic systems 				
4	Schlüsselqualifikationen <i>Key qualifications</i>				
	Sozialkompetenz	Methodenkompetenz	Selbstkompetenz / Personenkompetenz	Interkulturelle Kompetenz	Medienkompetenz
		X	X		
5	Lehrveranstaltung/ -methoden <i>Course type and methods</i> Vorlesung mit Übungen, auch am PC und an Hardware				
6	Vorbedingungen / Vorkenntnisse <i>Prerequisites</i> Mathematik I, II, III und alle Grundvorlesungen mit mathematisch-technischem Inhalt				
7	Arbeitsmittel / Literatur <i>Required material / Literature</i> Auszüge aus verschiedenen einschlägigen Lehrbüchern				

Detailinformationen																				
8	Inhalte <i>Course topics</i> <ul style="list-style-type: none"> Mathematical description of dynamic systems Nonlinear and linear systems of differential equations, simple technical examples, behavior of the solution, controlled and observed systems, equilibrium points and linearization Simulation of dynamic systems One step methods, discretization error and convergence, implementation with MATLAB, simulation with SIMULINK block diagrams, hardware in the loop Methods to derive a mathematical model Mechanical systems: bilances of forces and torques, equations of Euler-Lagrange Examples: Spring-mass-damper system, pendulum, crane positioning system, anti blocking system Thermal systems: Heat flow bilances Examples: Heating of a dc motor, heat exchanger, heating of a thin rod Fluid systems: mass flow bilances Examples: Pressure container, three-tank-system Electrical systems: Voltage and current bilances Example: RLC circuit, RLC circuit with a nonlinear resistor Electromechanical systems: dc motor SIMULINK models for a selection of these examples General properties of nonlinear systems Stability of nonlinear systems, Lyapunov functions, stability of linear systems, Lyapunovs indirect method, phase portraits, periodic solutions, limit cycles General properties of linear systems Solution formula, step response, frequency response, transfer functions, MATLAB tools, Case studie: Rotational pendelum (with laboratory experiment) Equations of motion, linearization, transfer functions, SIMULINK block diagram, set-up of the experiment, comparision of simulated and measured results 																			
9	Prüfungsform <i>Assessment</i> Klausur																			
10	Voraussetzung für die Vergabe von Kreditpunkten <i>Requirements for granting of credits</i> Erfolgreiches Bestehen der Klausur																			
11	Stellenwert der Note in der Endnote <i>Meaning of the mark concerning final exam</i> Anteilig 5/210																			
12	Weiterführende Veranstaltungen <i>Related courses</i> Automatic Control Systems I																			
13	Bezug zu Zielen des Studiengangs <i>Related objectives of the study program / Outcomes</i>																			
14	Zuordnung <i>Classification</i> <table border="1" style="width:100%; border-collapse: collapse;"> <thead> <tr> <th style="width:12.5%;">Mathematik & Naturwissenschaft</th> <th style="width:12.5%;">Ingenieurwissenschaften</th> <th style="width:12.5%;">Ingenieur-anwendungen</th> <th style="width:12.5%;">Entwicklung & Konstruktion</th> <th style="width:12.5%;">Werkstoffe</th> <th style="width:12.5%;">Wirtschaft, Management, Sprachen</th> <th style="width:12.5%;">Anderes</th> </tr> </thead> <tbody> <tr> <td></td> <td style="text-align:center">X</td> <td style="text-align:center">X</td> <td style="text-align:center">X</td> <td></td> <td></td> <td></td> </tr> </tbody> </table>						Mathematik & Naturwissenschaft	Ingenieurwissenschaften	Ingenieur-anwendungen	Entwicklung & Konstruktion	Werkstoffe	Wirtschaft, Management, Sprachen	Anderes		X	X	X			
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15	Modulbeauftragter / Lehrpersonen <i>Responsible person / Lecturers</i> Prof. Dr. Mackenroth																			